# **UM220-IV MO**

Industrial Grade Multi-GNSS
Navigation and Positioning Module





9.7 x 10.1 x 2.2 mm

### **Product Characteristics**

- » Super small packaging
- » Compact design, small size
- » Excellent performance, supporting single-system positioning and multi-system positioning
- » Anti-jamming technology, which enables the module to work stably in complex electromagnetic environments
- » Low power consumption
- » Suitable for large-scale applications that require high performance, small size and low cost

#### **Applications**



Tracker



Vehicle Navigation

## **Brief Introduction**

UM220-IV M0 is a multi-system compact navigation module designed for the automotive market. As the fourth generation of GNSS navigation and positioning module, UM220-IV M0 is based on Unicore's proprietary GNSS SoC UC6226. It is highly integrated, with low power consumption, anti-interference design, compact size, and is suitable for applications requiring low cost.

#### **Ordering Information**

Supply at multiples of 1000 pieces

10 GND	nRESET 9
11 RF_IN	VCC 8
	UM220-IV M0
12 GND	VCC_IO 7
13 ANTON	V_BCKP 6
14 VCC_RF	GPIO1 5
15 GPIO2	TIME PULSE 4
16 SDA	RXD 3
17 SCL	TXD 2
18 RSV	GND 1

## **Physical Specifications**

Dimensions	9.7 x 10.1 x 2.2 mm
Package	18 pin SMD
Temperature	Operating -40 °C ~ +85 °
	Storage -45 °C ~ +90 °C

# **Electrical Specifications**

Voltage	3.0 V ~ 3.6 V DC
LNA	3.0 V ~ 3.3 V, <100 mA
Power Consumption4	90 mW

#### **Functional Ports**

1 x UART	1 x 1PPS
Data Format: NMEA 0183	
Unicore	

#### **Functional Characteristics**

Passive Antenna, Active Antenna,
AGNSS *

NOTE: Supported by specific firmware

1 Simultaneously running three systems at most. Using command to switch between BDS and GLONASS.

2 Open sky.

3 Typical value < 30 m/s open sky.

4 Open sky, continuous tracking.

#### **Performance Specifications**

Channel	Based on 64-Channel SoC - UFirebird	
Frequency <sup>1</sup>	GPS L1	
	GLONASS G1	
	BDS B1	
	Galileo E1	
	QZSS	
	SBAS	
Modes	Single-System Positioning	
	Multi-System Positioning	
	Cold Start: < 28 s	
Time to First Fix (TTFF) <sup>2</sup>	AGNSS < 4 s	
	Hot Start < 1 s	
	Reacquisition: < 1 s	
Update Rate	1 Hz	
Positioning Accuracy <sup>3</sup>	2.0 m CEP(Dual-System Horizontal)	
Velocity	0.1 m/s (GNSS)	
Accuracy3(RMS)	0.1 11/5 (01933)	
1PPS	Support	
Sensitivity	GNSS	
Tracking	-161 dBm	
Acquisition	-146 dBm	
Hot Start	-151 dBm	
Reacquisition	-158 dBm	